Constructible Sheaves and Exit Paths (after Lurie)

Sasha Yom Din

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1 Remarks and notations

This text just follows Lurie's "Higher Algebra", appendix A ("Constructible Sheaves and Exit Paths").

There might be errors, inaccuracies, and unpleasancies in the following text. I will be happy if you let me know about it.

In this text, proofs are "proofs".

We denote by (\cdot, \cdot) the mapping spaces in different ∞ -categories, and by 1 the final object.

2 Presentable ∞ -categories

Presentable ∞ -categories are, in particular, cocomplete and complete.

A cocontinuous functor between presentable ∞ -categories has a right adjoint.

An accessible continuous functor between presentable ∞ -categories has a left adjoint. Accessibility is a technical condition (it means that the functor commutes with κ -filtered colimits for some regular cardinal κ); It suffices for us to know that a functor which admits a left or right adjoint is accessible, and a composition of accessible functors is accessible.

3 ∞ -Topoi

3.1 ∞ -Topoi and geometric morphisms

An ∞ -topos is an ∞ -category with extra properties. It is, in particular, presentable. Also, pull-backs commute with small colimits (if $x \to y$ is an arrow in an ∞ -topos, then $\cdot \times_y x$ commutes with small colimits).

A geometric morphism $\sigma: \mathcal{X} \to \mathcal{Y}$ between ∞ -topoi is, by definition, an adjoint pair $\sigma^*: \mathcal{X} \rightleftharpoons \mathcal{Y}: \sigma_*$, such that σ^* commutes with finite limits.

3.2 The ∞ -topos of spaces

We denote by S the ∞ -topos of spaces (the coherent nerve of the simplicial category of Kan complexes). It is final in the category of ∞ -topoi - every ∞ -topos admits a (up to homotopy) unique geometric morphism to S.

Let \mathcal{X} be an ∞ -topos and $\pi: \mathcal{X} \to \mathcal{S}$ the geometric morphism to \mathcal{S} (we will always denote it by π in what follows). One might call π_* the global sections fuentor; it can be identified with $(1,\cdot)$ (since $\pi_*(x) = (1,\pi_*x) = (\pi^*1,x) = (1,x)$). We might call π^* the constant object functor; it can be identified with $s \mapsto colim_s 1$ (sending a Kan complex s to the colimit over s, thought of as an indexing ∞ -category, of the constant diagarm with value 1).

3.3 Essential geometric morphisms

A geometric morphism $\pi: \mathcal{X} \to \mathcal{Y}$ is called essential, if π^* admits a left adjoint. We denote then this left adjoint by $\pi_!$.

3.4 Etale geometric morphisms

Let \mathcal{X} be an ∞ -topos. Let $u \in \mathcal{X}$. We will consider the over- ∞ -category $\mathcal{X}_{/u}$. Let us recall that the forgetful functor $\mathcal{X}_{/u} \to \mathcal{X}$ reflects equivalences and commutes with colimits.

The over-category $\mathcal{X}_{/u}$ is an ∞ -topos. We have an essential geometric morphism $j: \mathcal{X}_{/u} \to \mathcal{X}$. j^* is given by $j^*(x) = x \times u$ (equipped with the second projection). $j_!$ is just the forgetful functor. j_* seems not to be describable by a "simple formula".

If $\sigma: \mathcal{X} \to \mathcal{Y}$ is a geometric morphisms of ∞ -topoi and $u \in \mathcal{Y}$, then we have a pullback square (in an appropriately understood category of ∞ -topoi)

$$\begin{array}{ccc} \mathcal{X}_{/\sigma^*u} & \longrightarrow \mathcal{Y}_{/u} \\ \downarrow & & \downarrow \\ \mathcal{X} & \longrightarrow \mathcal{Y} \end{array}$$

Let us also note that if we consider $j: \mathcal{X}_{/u} \to \mathcal{X}$, then we can identify $(u,x) = (\pi \circ j)_* j^* x$ (a generalization of $(1,x) = \pi_* x$).

3.5 Coverings

Let \mathcal{X} be an ∞ -topos. Let $(u_{\alpha} \to 1)$ be a family of morphisms. Such a family is called a covering if $\coprod u_{\alpha} \to 1$ is an effective epimorphism $(a \to b)$ is called an effective epimorphism if b is the coequalizer of the Cech diagram $\ldots \to a \times_b a \times_b a \to a \times_b a \to a$.

4 Shape

4.1

Let \mathcal{X} be an ∞ -topos. We will call \mathcal{X} of constant shape if $\pi_* \circ \pi^*$ is corepresentable. The corepresenting object is then called the shape of \mathcal{X} .

We will call \mathcal{X} locally of constant shape if $\mathcal{X}_{/u}$ is of constant shape for every $u \in \mathcal{X}$.

Claim 4.1. Let \mathcal{X} be an ∞ -topos. Then \mathcal{X} is locally of constant shape if and only if π is essential.

Proof. Let $u \in \mathcal{X}$ and denote as usual $j: \mathcal{X}_{/u} \to \mathcal{X}$ and $\pi: \mathcal{X} \to \mathcal{S}$. Also, denote $\rho = \pi \circ j$ (it is the unique geometric morphism $\mathcal{X}_{/u} \to \mathcal{S}$). The sought for $\pi_! u$ should satisfy $(\pi_! u, s) = (u, \pi^* s) = (pi \circ j)_* j^* (\pi^* s) = \rho_* \rho^* s$. So, we see that $\pi_!$ exists if and only if $\rho_* \rho^*$ is corepresentable for every $u \in \mathcal{X}$, and that $\pi_!(u)$ is then the shape of $\mathcal{X}_{/u}$.

So, $\pi_! 1$ is the shape of \mathcal{X} . It can also be called the fundamental ∞ -groupoid of \mathcal{X} .

There is a projection formula:

Claim 4.2. Let \mathcal{X} be an ∞ -topos locally of constant shape. Then for any $s \in \mathcal{S}$, $x \in \mathcal{X}$ and arrows $s \to t$ and $\pi_! x \to t$,, the natural arrow:

$$\pi_!(x \times_{\pi^*t} \pi^*s) \to (\pi_!x) \times_t s$$

is an equivalence.

Proof. The first step of devissage is to reduce to t being equal to 1. Write $t = colim(t_{\alpha})$, with t_{α} contractible (i.e final in \mathcal{S}). Then $x = colim(x \times_{\pi^*t} \pi^*t_{\alpha})$ (as objects in $\mathcal{X}_{/\pi^*t}$). Since both sides are cocontinuous in x, this reduces us to show the claim for a situation where $\pi_! x \to t$ has a factorization $\pi_! x \to t_1 \to t$, where t_1 is contractible. But then we can set $s_1 = s \times_t t_1$ and then the left side equals $\pi_! (x \times_{\pi^*t_1} \pi^*s_1)$ and the right side equals $\pi_! x \times_{t_1} s_1$, so that we can assume that t is contractible.

The second step of devissage is to reduce to s being equal to 1. Indeed, both sides are cocontinuous in s.

Now, when s = t = 1, the claim is trivial.

5 Locally Constant Objects

Definition 5.1. Let \mathcal{X} be an ∞ -topos. An object $x \in \mathcal{X}$ is called constant, if it is in the image of π^* . An object $x \in \mathcal{X}$ is called locally constant, if there exists a covering $(u_{\alpha} \to 1)$ such that $(j_{\alpha})^*x$ is a constant object in $\mathcal{X}_{/u_{\alpha}}$, for every α (where j_{α} denotes the usual geometric morphism $\mathcal{X}_{/u_{\alpha}} \to \mathcal{X}$).

Of course, pullbacks under geometric morphisms of locally constant objects are locally constant.

Lemma 5.2. Let \mathcal{X} be an ∞ -topos, $t \in \mathcal{S}$, and $\psi : \mathcal{X} \to \mathcal{S}_{/t}$ some geometric morphism. Then the image of ψ^* consists of locally constant objects.

Proof. Let us first fix an object $k \to t$ in $S_{/t}$, with k being contractible (i.e. a final object in S). Then if we consider the diagram

$$\begin{array}{ccc} \mathcal{X}_{/\psi^*k} & \longrightarrow \mathcal{S}_{/k} \\ \downarrow & & \downarrow \\ \mathcal{X} & \longrightarrow \mathcal{S}_{/t} \end{array}$$

and notice that $S_{/k}$ is equivalent to S, we realize that objects in the image of ψ^* become constant when pullbacked to $\mathcal{X}_{/\psi^*k}$. All what is left to do is to find a covering of t by contractible objects; One can take the covering by simplices.

Lemma 5.3. Let \mathcal{X}, \mathcal{Y} be ∞ -topoi, and $\psi : \mathcal{X} \to \mathcal{Y}$ an essential geometric morphism such that $\psi_!(1) = 1$ and ψ^* is fully faithful. Then every locally constant object in \mathcal{X} is in the image of ψ^* .

Proof. Is this true? I tried to extract it from the text, but did not check details. Let $x \in \mathcal{X}$ be a locally constant object. Note that if x is actually constant, then it belongs to the inverse image under **any** geometric morphism (because the geometric morphism into \mathcal{S} factors through any ∞ -topos). We can find a relation $colim(v_{\beta}) = 1$ in \mathcal{X} , so that $(j_{\beta})^*x$ is a constant object in $\mathcal{X}_{/v_{\beta}}$ (we achieve it by considering a covering of 1 on which x is constant, and take the Cech nerve). Note that then $colim(\psi_{!}v_{\beta}) = 1$. I am not sure what exactly happens now; \mathcal{X} is the limit of $\mathcal{X}_{/v_{\beta}}$, \mathcal{Y} is the limit of $\mathcal{Y}_{/\psi_{!}v_{\beta}}$, and the fully-faithful functor ψ^* is the limit of fully-faithful functors $(\psi_{\beta})^*$. Thus it is enough to check for every β , where it is trivial since the object is already constant.

Let \mathcal{X} be an ∞ -topos of locally constant shape. Then the functor $\pi_!: \mathcal{X} \to \mathcal{S}$ induces a functor $\psi_!: \mathcal{X} = \mathcal{X}_{/1} \to \mathcal{S}_{/\pi_! 1}$. $\psi_!$ admits a right adjoint ψ^* , described by $\psi^*(s \to \pi_! 1) = (\pi^* s) \times_{\pi^* \pi_! 1} 1$. We see that ψ^* commutes with colimits, and hence admits a right adjoint ψ_* . Summarazing, we get an essential geometric morphism $\psi: \mathcal{X} \to \mathcal{S}_{/\pi_! 1}$.

Theorem 5.4. In the above assumptions and notation, ψ^* is fully faithful, and its image consists exactly of locally constant objects.

Proof. Let us show first that ψ^* is fully faithful. For this, we will show that $\psi_!\psi^* \to id$ is an equivalence, on every object. Indeed, if for an object $s \to \pi_! 1$, if we apply $\psi_!\psi^*$ to it we get $\pi_!(\pi^*s \times_{\pi^*\pi_! 1} 1) \to \pi_! 1$, and by the projection formula from above, it is equivalent to $s \to \pi_! 1$.

The second claim follows from the two lemmas above.

6 Topological spaces

6.1 Sheaves on topological spaces

Let X be a topological space. We have the partially ordered set U(X) of open subsets of X. We denote by PSh(X) the category of functors $U(X)^{op} \to \mathcal{S}$. It has a full subcategory Sh(X), consisting of objects $p \in PSh(X)$ which satisfy "descent". This just means that we take the biggest full subcategory in which for a covering (U_{α}) of X in the point-set-topological sense, the family $(U_{\alpha} \to X)$ will be a covering in the ∞ -topos sense.

Sh(X) is an ∞ -topos. Lurie notes that Sh(X) differs from the more common version - the one extracted from the local model structure. The later takes into account hypercovers. In general, the later is the hypercompletion of the former. I do not know for which class of spaces they coincide.

A morphism of topological spaces $X \to Y$ gives rise to a geometric morphism $Sh(X) \to Sh(Y)$. If U is an open subset of X, then $j: Sh(U) \to Sh(X)$ identifies with $Sh(X)_{/j,1} \to Sh(X)$.

6.2 Shape for topological spaces

Claim 6.1. Let X be a paracompact topological space. Then, considering the geometric morphism $\pi: Sh(X) \to \mathcal{S}$, we have $\pi_*\pi^*(s) = Map(X,|s|)$. Here, Map(Y,Z) is the Kan complex whose n-simplices are continuous maps $Y \times |\Delta^n| \to Z$.

Proof. Not from this appendix, but from "Higher topos theory".

Corollary 6.2. Let X be a paracompact topological space. Then Sh(X) has constant shape if and only if there exists a Kan complex k and a morphism $X \to |k|$ such that for every Kan complex s, the map $(k,s) = Map(|k|,|s|) \to Map(X,|s|)$ is an equivalence.

For example, if X is a paracompact topological space which has the homotopy type of a CW-complex, then Sh(X) has constant shape, being Sing(X). Indeed, the weak equivalence $|Sing(X)| \to X$ is then an homotopy equialence, thus we obtain a map $X \to |Sing(X)|$.

Definition 6.3. Let X be a paracompact topological space. We will say that X has singular shape if for every CW-complex Y, the map $Map(X,Y) \to Map(|Sing(X)|,Y)$ is an equivalence.

Thus, the remark above shows that a paracompact topological space which has the homotopy type of a CW-complex has singular shape.

Definition 6.4. Let X be a paracompact topological space. We will say that X is locally of singular shape if for every open subspace $U \subset X$, U has singular shape.

The lemma A.4.14 says that if we cover a paracompact topological space X by open subspaces, such that every finite intersection of them is of singular shape, then X is of singular shape. This shows, for example, that topological manifolds are locally of singular shape.

6.3 Description of the Galois correspondence

Let X be a paracompact topological space locally of singular shape. Then the ∞ -topos $\mathcal{S}_{/Sing(X)}$ is equivalent to the ∞ -topos of locally constant sheaves on X. For $s \in \mathcal{S}_{/Sing(X)}$, the corresponding sheaf can informally be described as having sections $(Sing(U), s)_{Sing(X)}$ on an open subset U (it is a mapping space in the ∞ -category $\mathcal{S}_{/Sing(X)}$).

We can perefer a different model for $\mathcal{S}_{/Sing(X)}$ (I hope that what I tell here is correct). Note that in the current model $\mathcal{S}_{/t}$, objects are spaces together with a morphism to t. Morphisms are, morally, morphisms which commute with the structure map to t up to homotopy. Instead, we can consider only fibrations over t, but then consider only morphisms which commute with the structure map on the nose. I.e., let us consider the simplicial category of Kan fibrations over t, and denote it by $\mathcal{S}_{/t}^{simp}$.

In such terms, the association to an space over Sing(X) of a sheaf on X becomes more concrete. To a Kan fibration $s \to Sing(X)$ we associate the sheaf $U \mapsto Hom_{S_{/Sing(X)}^{simp}}(Sing(U), s)$. So our sheaf is an actual 1-functor, so to speak.

7 Constructible sheaves

7.1 Stratifications

Let A be a partially ordered set. We can regard A as a topological space by declaring a set $U \subset A$ to be open if $x \in U$ and $x \leq y$ imply $y \in U$.

Definition 7.1. An A-stratification of a topological space X is a morphism of topological spaces $X \to A$. $X \to A$ is then called a stratified topological space. The strata X_a are the inverse images of singletons $\{a\} \in A$. There is an obvious notion of a morphism of stratified spaces (which includes a morphism of the partially ordered sets and a morphism of the spaces, commuting appropriately).

Definition 7.2. Let $X \to A$ be a stratified topological space. It is said to be conically stratified if...

7.2 Constructible sheaves

Definition 7.3. Let $X \to A$ be a stratified topological space. A sheaf $p \in Sh(X)$ is called A-constructible if $(i_a)^*p$ is locally constant, for all $i_a : Sh(X_a) \to Sh(X_a)$

Sh(X) (the geometric morphism induced by the inclusion $X_a \to X$). We denote by $Sh^A(X)$ the full ∞ -subcategory of Sh(X) consisting of A-constructible sheaves.

7.3 Exit path category

Let us stratify $|\Delta^n| = \{(t_0, \dots, t_n)|t_0 + \dots + t_n = 1, t_i \ge 0\}$ by $\{0, \dots, n\}$, by sending each vector to the index of the last non-zero entry.

Definition 7.4. Let $X \to A$ be a stratified topological space. We define a simplicial subset $Sing^A(X) \subset Sing(X)$ as follows. An n-simplex $|\Delta^n| \to X$ will belong to $Sing^A(X)$ if and only if this morphism extends to a morphism of stratified spaces.

Claim 7.5. Let $X \to A$ be a conically stratified topological space. Then $Sing^A(X)$ is an ∞ -category.

7.4 The theorem

Let $X \to A$ be a conically stratified topological space. Suppose that A is finite (Lurie deals more generally with A which satisfies ascending chain condition). Suppose that X is a paracompact topological space locally of singular shape.

Then the ∞ -category $Sh^A(X)$ is equivalent to the ∞ -category $\mathcal{S}_{/Sing^A(X)}$. Here, for an ∞ -category t, we denote by $\mathcal{S}_{/t}$ the ∞ -category which classifies functors from t to \mathcal{S} . So, a possible model for $\mathcal{S}_{/t}$ is the coherent nerve of the simplicial category of left fibrations to t.

References

- [1] Lurie, Higher Algebra, appendix A
- [2] Lurie, Higher Topos Theory